

FEATURES

- Access Times of 150, 200, 250 and 350ns
- Single 5V±10% Power Supply
- Byte Write Cycle Time - 10 ms Maximum
- Low Power CMOS:
 - 60 mA Active Current
 - 250 µA Standby Current
- Fast Write Cycle Time - $\overline{\text{DATA}}$ Polling
- CMOS & TTL Compatible Inputs and Outputs

- Endurance:
 - 10,000 Write Cycles
 - 100,000 Write Cycles (optional)
- Data Retention: 10 Years
- Available in the following packages:
 - 24-Pin 600 mil Ceramic DIP
 - 32-Pin Ceramic LCC (450x550 mils)

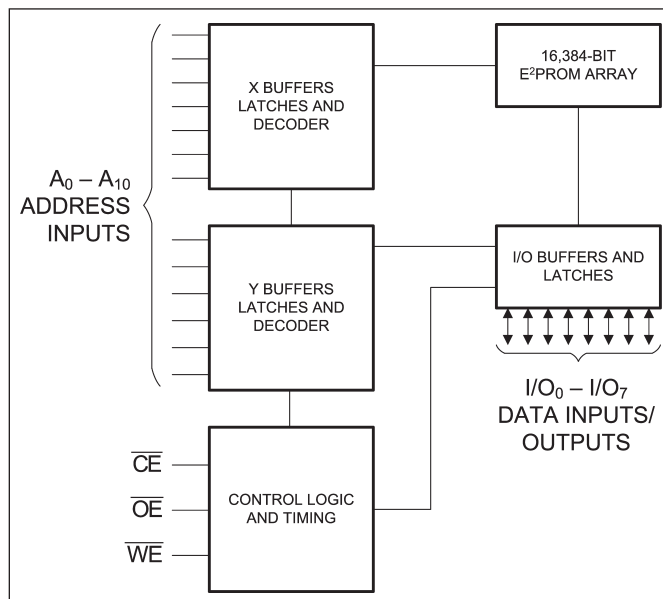


DESCRIPTION

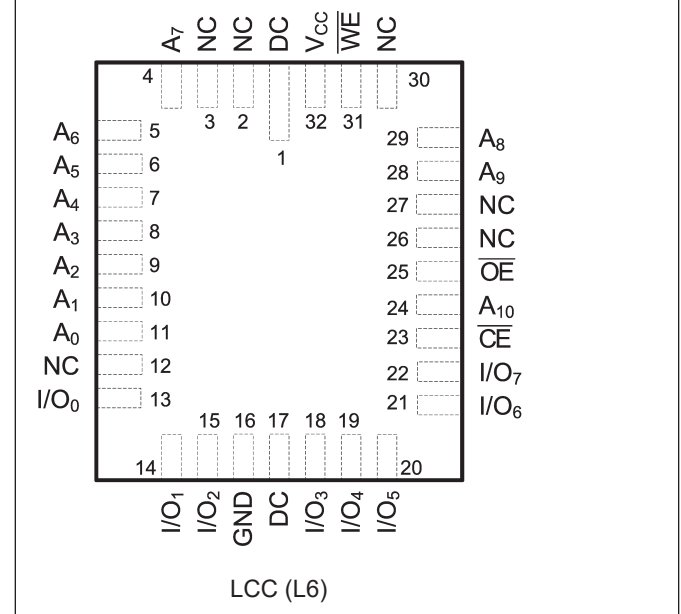
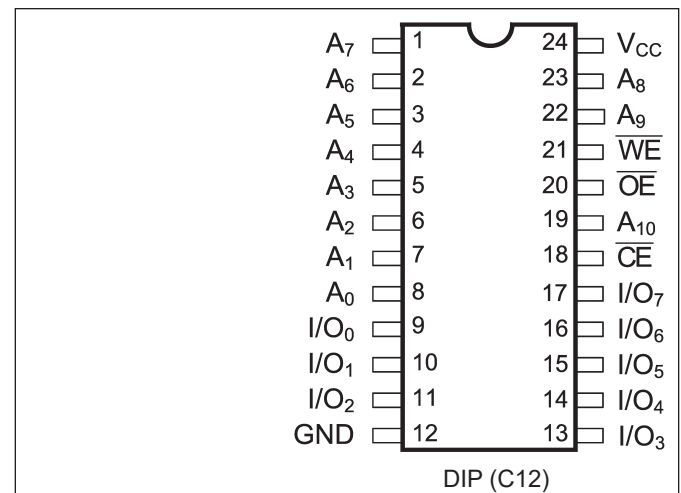
The PYA28C16B is a 5 Volt 2Kx8 EEPROM. The PY-A28C16B is a 16K memory organized as 2,048 words by 8 bits. Data Retention is 10 years. The device is available in a 24-pin 600 mil wide Ceramic DIP and a 32-pin LCC.



FUNCTIONAL BLOCK DIAGRAM



PIN CONFIGURATIONS





OPERATION

READ

Read operations are initiated by both \overline{OE} and \overline{CE} LOW. The read operation is terminated by either \overline{CE} or \overline{OE} returning HIGH. This two line control architecture eliminates bus contention in a system environment. The data bus will be in a high impedance state when either \overline{OE} or \overline{CE} is HIGH.

BYTE WRITE

Write operations are initiated when both \overline{CE} and \overline{WE} are LOW and \overline{OE} is HIGH. The PYA28C16B supports both a \overline{CE} and \overline{WE} controlled write cycle. That is, the address is latched by the falling edge of either \overline{CE} or \overline{WE} , whichever occurs last. Similarly, the data is latched internally by the rising edge of either \overline{CE} or \overline{WE} , whichever occurs first. A byte write operation, once initiated, will automatically continue to completion.

CHIP CLEAR

The contents of the entire memory of the PYA28C16B may be set to the high state by the CHIP CLEAR operation. By setting \overline{CE} low and \overline{OE} to 12 volts, the chip is cleared when a 10 msec low pulse is applied to \overline{WE} .

DEVICE IDENTIFICATION

An extra 32 bytes of EEPROM memory are available to the user for device identification. By raising A_9 to $12 \pm 0.5V$ and using address locations 7E0H to 7FFH the additional bytes may be written to or read from in the same manner as the regular memory array.

DATA POLLING

The PYA28C16B features \overline{DATA} Polling as a method to indicate to the host system that the byte write cycle has completed. \overline{DATA} Polling allows a simple bit test operation to determine the status of the PYA28C16B, eliminating additional interrupts or external hardware. During the internal programming cycle, any attempt to read the last byte written will produce the complement of that data on I/O_7 (i.e., write data=0xxx xxxx, read data=1xxx xxxx). Once the programming cycle is complete, I/O_7 will reflect true data.

MAXIMUM RATINGS⁽¹⁾

Sym	Parameter	Value	Unit
V_{CC}	Power Supply Pin with Respect to GND	-0.3 to +6.25	V
V_{TERM}	Terminal Voltage with Respect to GND (up to 6.25V)	-0.5 to +6.25	V
T_A	Operating Temperature	-55 to +125	°C
T_{BIAS}	Temperature Under Bias	-55 to +125	°C
T_{STG}	Storage Temperature	-65 to +150	°C
P_T	Power Dissipation	1.0	W
I_{OUT}	DC Output Current	50	mA

RECOMMENDED OPERATING CONDITIONS

Grade ⁽²⁾	Ambient Temp	GND	V_{CC}
Military	-55°C to +125°C	0V	5.0V \pm 10%

CAPACITANCES⁽⁴⁾

($V_{CC} = 5.0V$, $T_A = 25^\circ C$, $f = 1.0MHz$)

Sym	Parameter	Conditions	Typ	Unit
C_{IN}	Input Capacitance	$V_{IN} = 0V$	10	pF
C_{OUT}	Output Capacitance	$V_{OUT} = 0V$	10	pF



DC ELECTRICAL CHARACTERISTICS

(Over Recommended Operating Temperature & Supply Voltage)⁽²⁾

Sym	Parameter	Test Conditions	PYA28C16B		Unit
			Min	Max	
V _{IH}	Input High Voltage		2.0	V _{CC} + 0.3	V
V _{IL}	Input Low Voltage		-0.5 ⁽³⁾	0.8	V
V _{HC}	CMOS Input High Voltage		V _{CC} - 0.2	V _{CC} + 0.5	V
V _{LC}	CMOS Input Low Voltage		-0.5 ⁽³⁾	0.2	V
V _{OL}	Output Low Voltage (TTL Load)	I _{OL} = +2.1 mA, V _{CC} = Min		0.45	V
V _{OH}	Output High Voltage (TTL Load)	I _{OH} = -0.4 mA, V _{CC} = Min	2.4		V
I _{LI}	Input Leakage Current	V _{CC} = Max V _{IN} = GND to V _{CC}	-10	+10	μA
I _{LO}	Output Leakage Current	V _{CC} = Max, $\overline{CE} = V_{IH}$, V _{OUT} = GND to V _{CC}	-10	+10	μA
I _{SB}	Standby Power Supply Current (TTL Input Levels)	$\overline{CE} \geq V_{IH}$, $\overline{OE} = V_{IL}$, V _{CC} = Max, f = Max, Outputs Open	—	5	mA
I _{SB1}	Standby Power Supply Current (CMOS Input Levels)	$\overline{CE} \geq V_{HC}$, V _{CC} = Max, f = 0, Outputs Open, V _{IN} ≤ V _{LC} or V _{IN} ≥ V _{HC}	—	250	μA
I _{CC}	Supply Current	$\overline{CE} = \overline{OE} = V_{IL}$, $\overline{WE} = V_{IH}$, All I/O's = Open, Inputs = V _{CC} = 5.5V	—	60	mA

Notes:

- Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to MAXIMUM rating conditions for extended periods may affect reliability.
- Extended temperature operation guaranteed with 400 linear feet per minute of air flow.
- Transient inputs with V_{IL} and I_{IL} not more negative than -3.0V and -100mA, respectively, are permissible for pulse widths up to 20ns.
- This parameter is sampled and not 100% tested.

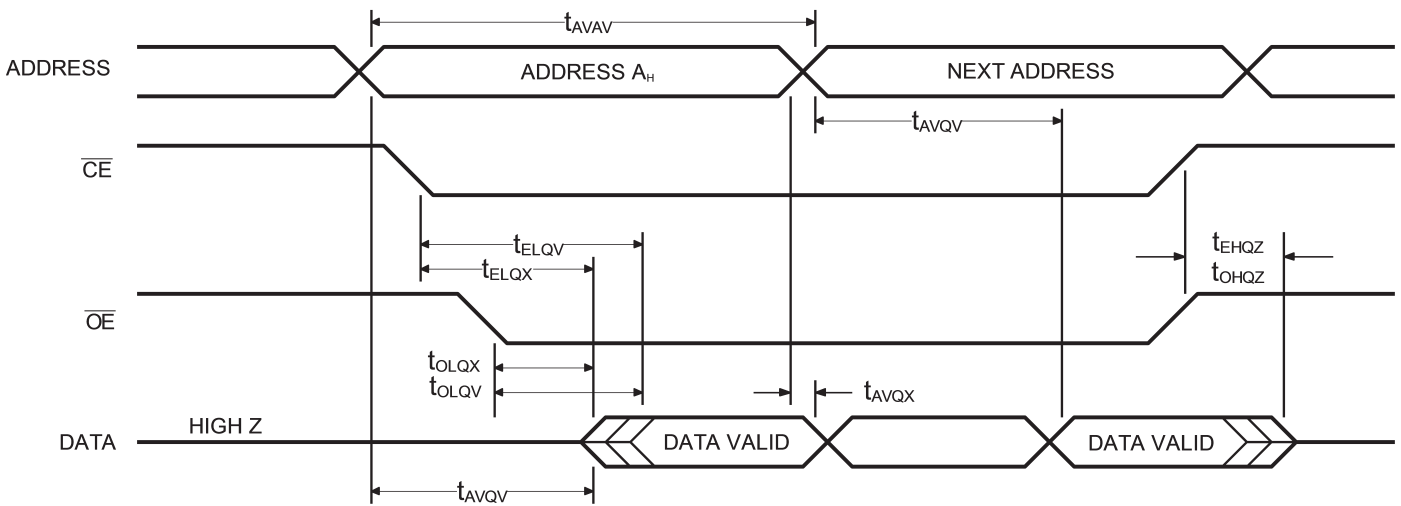


AC ELECTRICAL CHARACTERISTICS—READ CYCLE

($V_{CC} = 5V \pm 10\%$, All Temperature Ranges)⁽²⁾

Sym	Parameter	-150		-200		-250		-350		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
t_{AVAV}	Read Cycle Time	150		200		250		350		ns
t_{AVQV}	Address Access Time		150		200		250		350	ns
t_{ELQV}	Chip Enable Access Time		150		200		250		350	ns
t_{OLQV}	Output Enable Access Time		80		100		100		100	ns
t_{ELQX}	Chip Enable to Output in Low Z	0		0		0		0		ns
t_{EHQZ}	Chip Disable to Output in High Z		55		60		65		70	ns
t_{OLQX}	Output Enable to Output in Low Z	0		0		0		0		ns
t_{OHQZ}	Output Disable to Output in High Z		55		60		65		70	ns
t_{AVQX}	Output Hold from Address Change	0		0		0		0		ns

TIMING WAVEFORM OF READ CYCLE

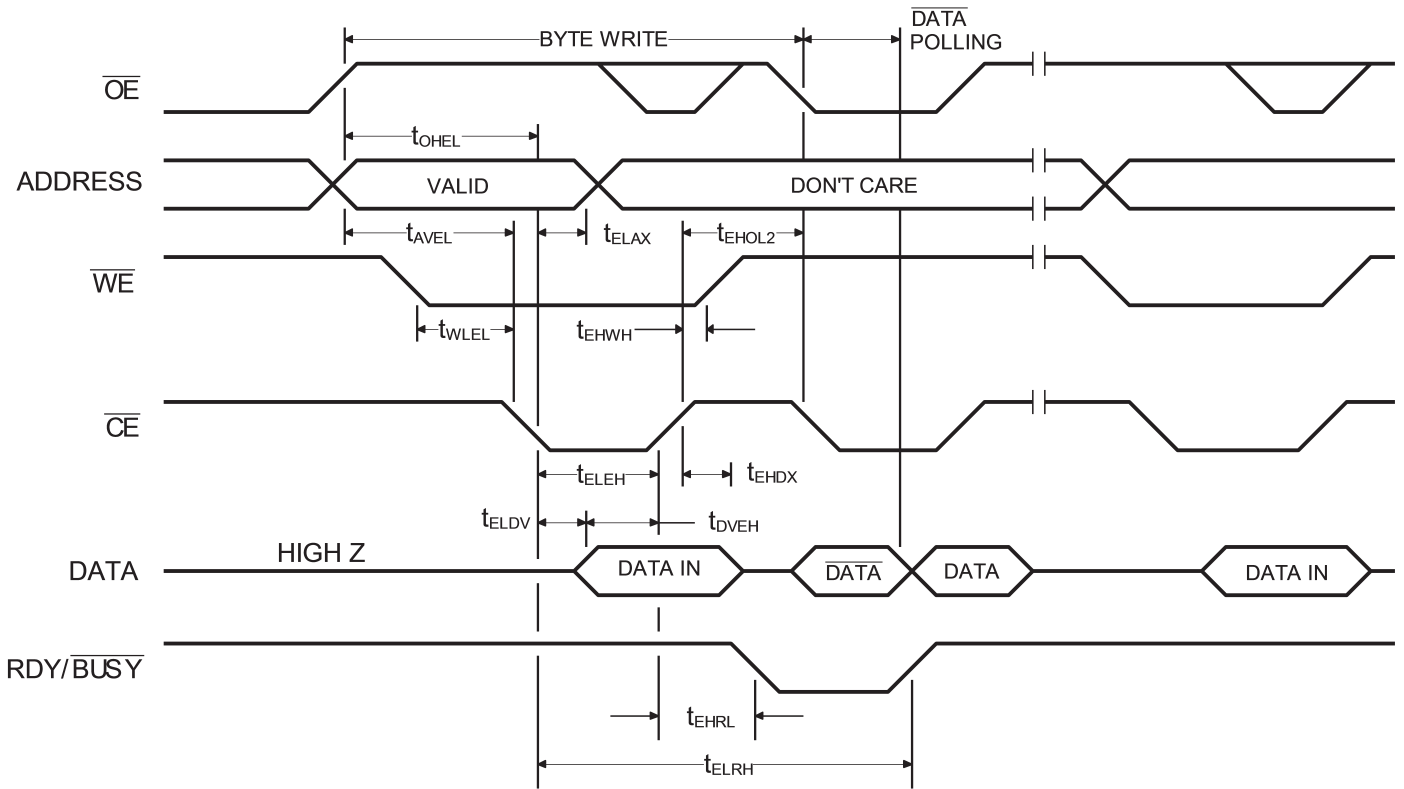


**AC CHARACTERISTICS—WRITE CYCLE** $(V_{CC} = 5V \pm 10\%, \text{ All Temperature Ranges})^{(2)}$

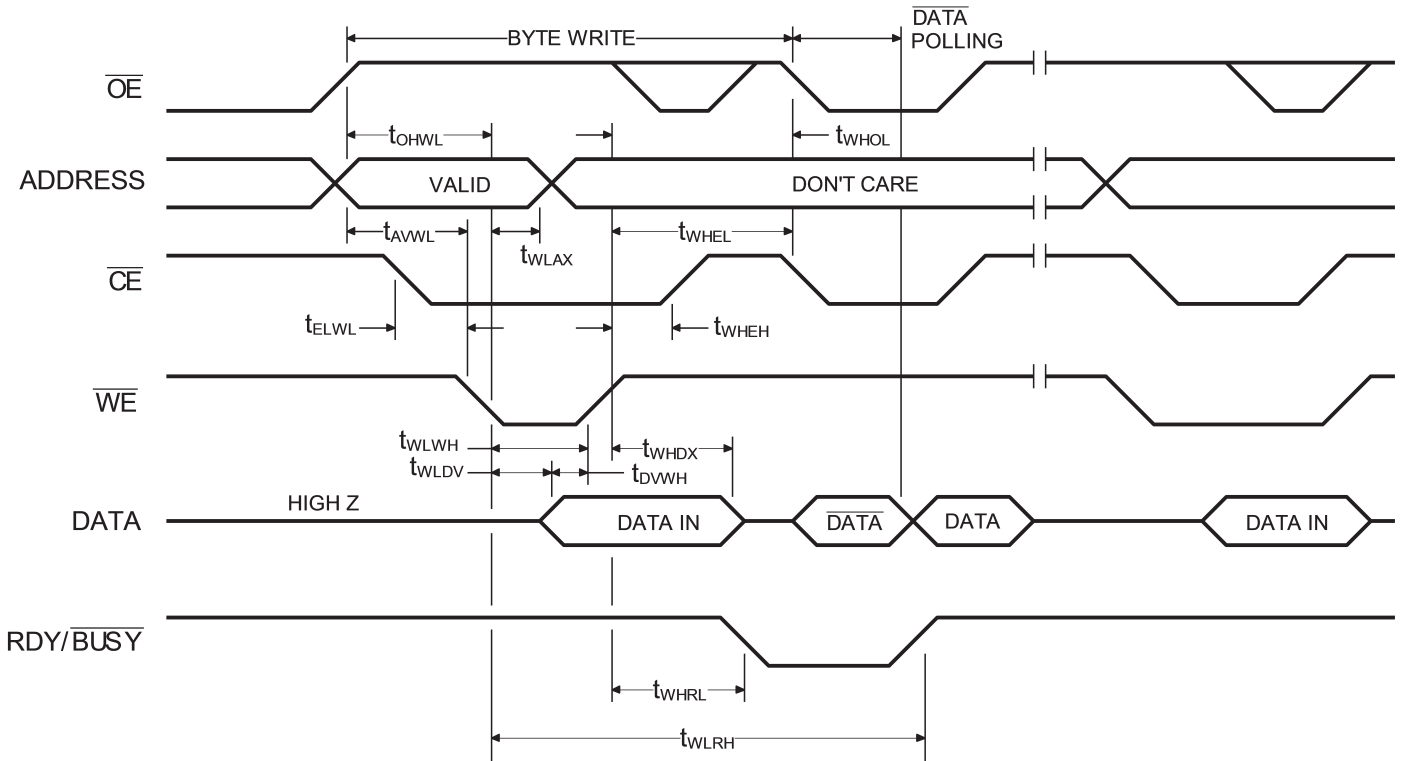
Symbol	Parameter	150 / 200 / 250 / 350		Unit
		Min	Max	
t_{ELRH} t_{WLRH}	Write Cycle Time		10	ms
t_{AVEL} t_{AVWL}	Address Setup Time	10		ns
t_{ELAX} t_{WLAX}	Address Hold Time	50		ns
t_{WLEL}	Write Setup Time	0		ns
t_{WHEH}	Write Hold Time	0		ns
t_{OHEL} t_{OHWL}	\overline{OE} Setup Time	10		ns
t_{WHOL} t_{EHOL2}	\overline{OE} Hold Time	10		ns
t_{ELEH} t_{WLWH}	\overline{WE} Pulse Width	100	1000	ns
t_{DVEH} t_{DVWH}	Data Setup Time	50		ns
t_{EHDX} t_{WHDX}	Data Hold Time	10		ns
t_{ELWL}	\overline{CE} Setup Time	0		ns
t_{EHWH}	\overline{CE} Hold Time	0		ns
t_{EHRL} t_{WHRL}	Time to device busy		50	ns



TIMING WAVEFORM OF BYTE WRITE CYCLE (\overline{CE} CONTROLLED)



TIMING WAVEFORM OF BYTE WRITE CYCLE (\overline{WE} CONTROLLED)





AC TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	10ns
Input Timing Reference Level	1.5V
Output Timing Reference Level	1.5V
Output Load	See Figure 1

TRUTH TABLE

Mode	\overline{CE}	\overline{OE}	\overline{WE}	I/O
Read	L	L	H	D _{OUT}
Write	L	H	L	D _{IN}
Write Inhibit	X	L	X	—
Write Inhibit	X	X	H	—
Standby	H	X	X	High Z
Output Disable	X	H	X	High Z

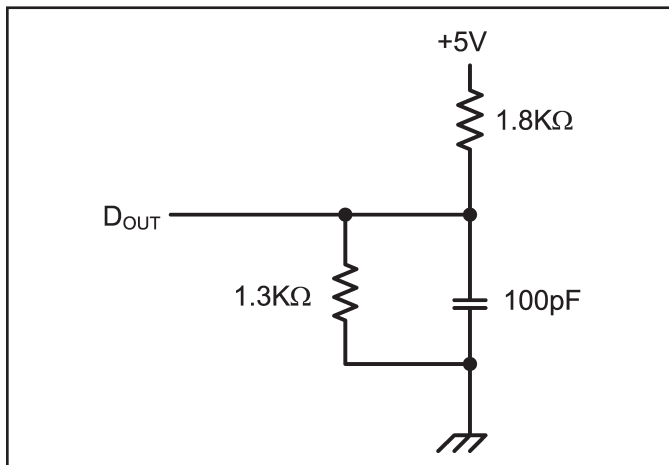
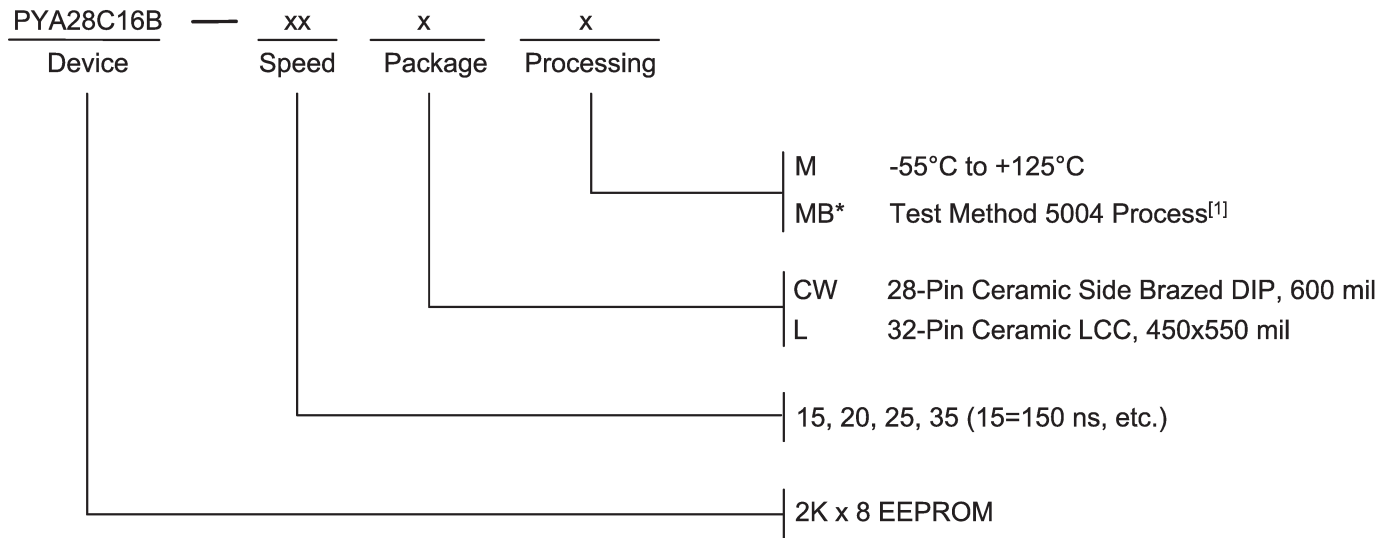


Figure 1. Output Load



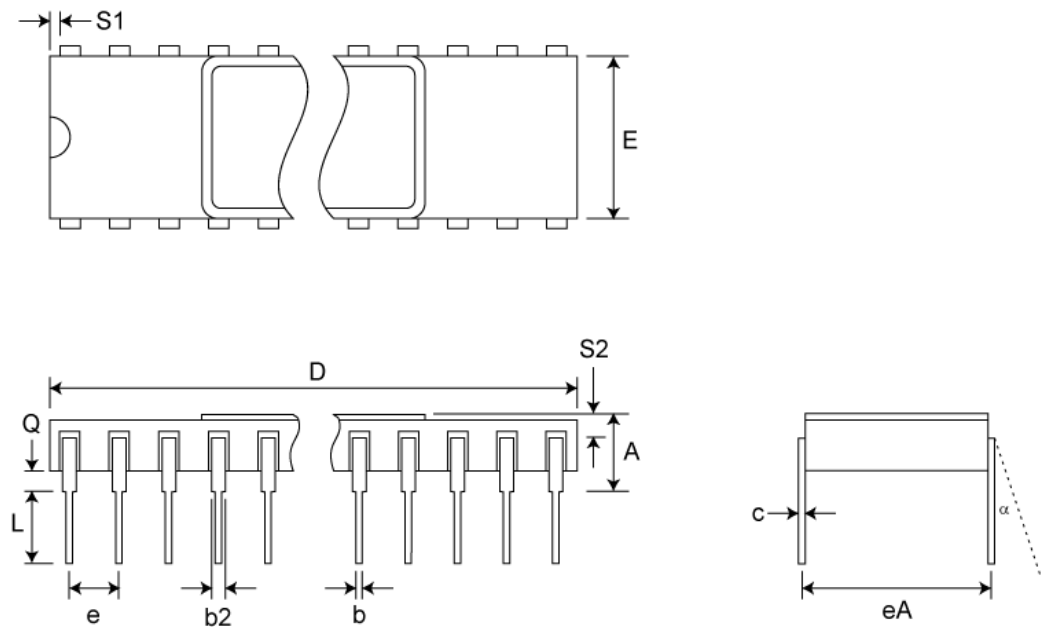
ORDERING INFORMATION



[1] Parts are not MIL-STD-883 compliant. Parts are processed per Test Method 5004

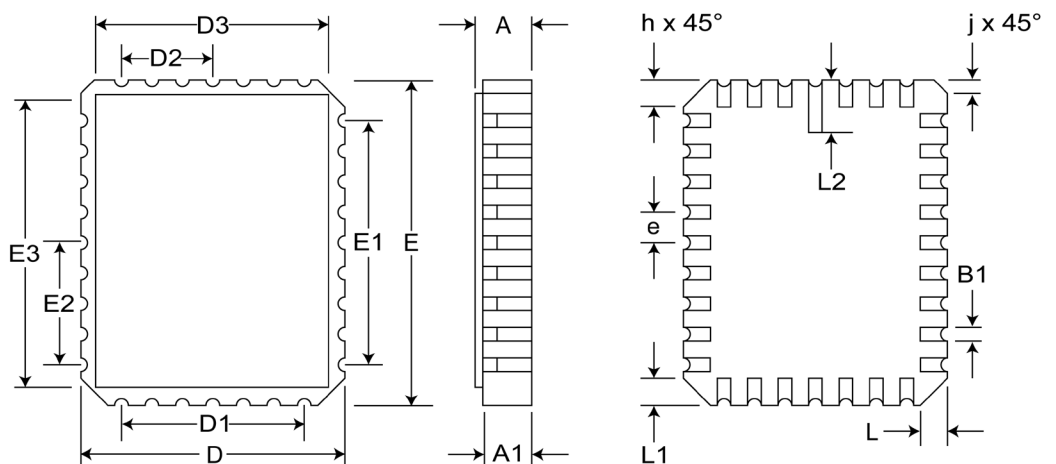
SIDE BRAZED DUAL IN-LINE PACKAGE (600 mils)

Pkg #	C12	
# Pins	24 (600 mil)	
Symbol	Min	Max
A	-	0.232
b	0.014	0.026
b2	0.045	0.065
C	0.008	0.018
D	-	1.290
E	0.500	0.610
eA	0.600 BSC	
e	0.100 BSC	
L	0.125	0.200
Q	0.015	0.060
S1	0.005	-
S2	0.005	-



Pkg #	L6	
# Pins	32	
Symbol	Min	Max
A	0.060	0.075
A1	0.050	0.065
B1	0.022	0.028
D	0.442	0.458
D1	0.300 BSC	
D2	0.150 BSC	
D3	-	0.458
E	0.540	0.560
E1	0.400 BSC	
E2	0.200 BSC	
E3	-	0.558
e	0.050 BSC	
h	0.040 REF	
j	0.020 REF	
L	0.045	0.055
L1	0.045	0.055
L2	0.075	0.095
ND	7	
NE	9	

RECTANGULAR LEADLESS CHIP CARRIER



**REVISIONS**

DOCUMENT NUMBER	EEPROM109
DOCUMENT TITLE	PYA28C16B - 2K x 8 EEPROM

REV	ISSUE DATE	ORIGINATOR	DESCRIPTION OF CHANGE
OR	Oct 2012	JDB	New Data Sheet
01	Feb 2016	JDB	Added MB* Processing
02	Feb 2016	JDB	Removed MB Processing
03	Jun 2016	JDB	Corrected Ordering Information
04	May 2018	JDB	Corrected CMOS Standby Current